

IO 420

PROGRAMMABLE FOUR-CHANNEL, H-BRIDGE, PWM MOTOR CONTROLLER

DESCRIPTION

The IO 420 is a programmable four-channel, H-Bridge, PWM motor controller. The controller is used as a companion component to Appareo Gateway Telematic Control Unit (TCU) products to actuate hydraulics, spin motors, receive sensor feedback, and interface to system components over a CAN interface. It supports 5A per channel, provides frequency/analog/digital feedback, and is programmed through CAN.



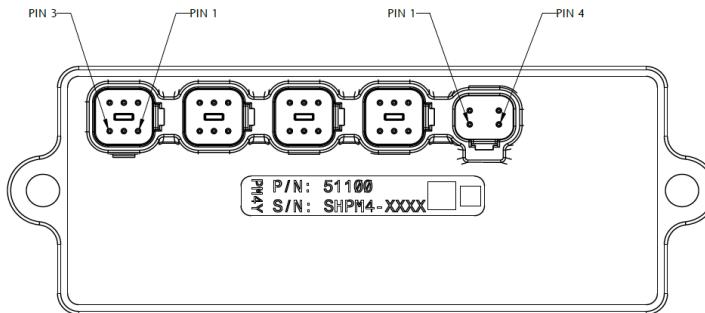
APPLICATIONS

The IO 420 was developed to drive DC motors and hydraulic valves on heavy machinery and agricultural implements. Its rugged design allows it to operate in harsh environmental conditions. The IO 420 integrates seamlessly with an Appareo Gateway, connecting to one of its six CAN ports.

FEATURES

- Four 5A, H-Bridge, PWM motor controllers
 - H-Bridge controllers can be ganged, allowing two 10A motor controllers
- Eight configurable inputs (2 per bank) for:
 - Analog input
 - Digital input
 - Frequency/rotary encoder
- Integrated speed control using input feedback
- 0% to 100% PWM operation per channel
- Bidirectional motor control with H-Bridge outputs
- Control Area Network (CAN) interface
- Automatic discovery and operation in Gateway ecosystem
- Engineered to IP69K environmental ratings

INPUT/OUTPUT



| Connector: Pin | I/O | Function |
|----------------|-----------|-----------------------------------|
| PIN: 1 | CAN_HIGH | CAN Bus High |
| PIN: 2 | CAN_LOW | CAN Bus Low |
| PIN: 3 | VIN | Input Voltage (12 V) |
| PIN: 4 | GND | Ground |
| POUT 1: 1 | HBRIDGE1+ | PWM Output 1 + |
| POUT 1: 2 | HBRIDGE1- | PWM Output 1 - |
| POUT 1: 3 | INPUT1A | Frequency/Analog/Digital Input 1A |
| POUT 1: 4 | INPUT1B | Frequency/Analog/Digital Input 1B |
| POUT 1: 5 | DO1 | Digital Out 1 |
| POUT 1: 6 | GND | Ground |
| POUT 2: 1 | HBRIDGE2+ | PWM Output 2 + |
| POUT 2: 2 | HBRIDGE2- | PWM Output 2 - |
| POUT 2: 3 | INPUT2A | Frequency/Analog/Digital Input 2A |
| POUT 2: 4 | INPUT2B | Frequency/Analog/Digital Input 2B |
| POUT 2: 5 | DO2 | Digital Out 2 |
| POUT 2: 6 | GND | Ground |
| POUT 3: 1 | HBRIDGE3+ | PWM Output 3 + |
| POUT 3: 2 | HBRIDGE3- | PWM Output 3 - |
| POUT 3: 3 | INPUT3A | Frequency/Analog/Digital Input 3A |
| POUT 3: 4 | INPUT3B | Frequency/Analog/Digital Input 3B |
| POUT 3: 5 | DO3 | Digital Out 3 |
| POUT 3: 6 | GND | Ground |
| POUT 4: 1 | HBRIDGE4+ | PWM Output 4 + |
| POUT 4: 2 | HBRIDGE4- | PWM Output 4 - |
| POUT 4: 3 | INPUT4A | Frequency/Analog/Digital Input 4A |
| POUT 4: 4 | INPUT4B | Frequency/Analog/Digital Input 4B |
| POUT 4: 5 | DO4 | Digital Out 4 |
| POUT 4: 6 | GND | Ground |

ABSOLUTE MAXIMUM RATINGS

Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime.

| Parameter | Value | Unit |
|---------------------------|---------------|------|
| VIN to GND | -13.6 to 26.5 | V |
| CAN+, CAN-, to SGND | -0.3 to 16.5 | V |
| CAN+, CAN-, to VIN | -0.3 to 16.5 | V |
| CAN+ to CAN- | -0.3 to 16.5 | V |
| Configurable Input to GND | -0.3 to 16.5 | V |
| Storage Temperature | -55 to 105 | °C |
| Operating Temperature | -40 to 75 | °C |

ELECTRICAL SPECIFICATIONS

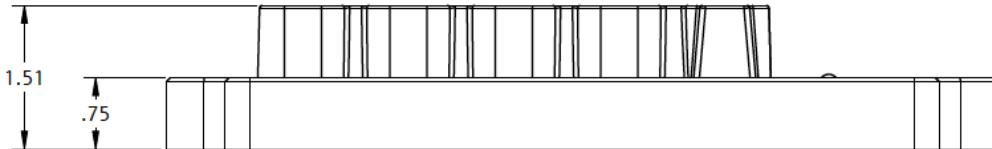
| Symbol | Parameter | Min | Typ | Max | Unit |
|--------------------------------------|---|-----|------|------|--------|
| POWER SUPPLY | | | | | |
| I _{IN} | Input current | | | 13 | A |
| V _{CC} | Supply voltage | 9 | 13.8 | 16 | V |
| t _{STARTUP} | Start-up time from power-on | | < 1 | 15 | second |
| CAN BUS | | | | | |
| V _{IH, CAN} | Input high voltage | 5 | | | V |
| V _{IL, CAN} | Input low voltage | | | 0.8 | V |
| f _{CAN} | CAN BAUD Rate | 125 | | 500 | Kbps |
| H-BRIDGE POWER OUTPUT | | | | | |
| I _{OUT} | Output current (100% duty cycle) | | | 5 | A |
| f _{OUT} | Output frequency range | 100 | | 5000 | Hz |
| f _{STEP} | Output frequency increments | | 100 | | Hz |
| D _{COUT} | Output duty cycle range | 0 | | 100 | % |
| D _{CSTEP} | Output duty cycle increments | | 2 | | % |
| H-BRIDGE OUTPUT CURRENT SENSE | | | | | |
| I _{CS,RANGE} | Current sense range | -5 | | 5 | A |
| I _{CS, ERROR} | Current sense error | | | 0.15 | A |
| H-BRIDGE CURRENT LIMITING | | | | | |
| I _{LIM} | Active current limiting threshold | 5.2 | 6.5 | 7.8 | A |
| I _{SCH} | High-side short circuit detection threshold | 11 | | | A |
| I _{SCL} | Low-side short circuit detection threshold | 8 | | | A |
| DIGITAL OUTPUT (8 - 16 VDC) | | | | | |
| I _{12VDC, OUT} | Digital output current | | | 100 | mA |
| I _{12VDC, CS} | Digital current sense precision | | 1 | | mA |

ELECTRICAL SPECIFICATIONS

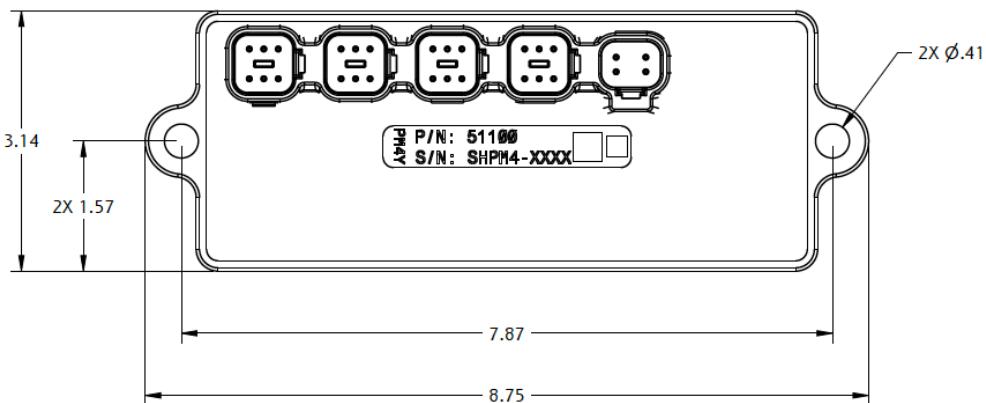
| Symbol | Parameter | Min | Typ | Max | Unit |
|---------------------------|---|------|------|------------|---------|
| CONFIGURABLE INPUT | | | | | |
| f_{IN} | Input frequency range | 16.6 | | 5,000 | Hz |
| f_{ERROR} | Input frequency error: 16.6 to 120 Hz 120.1 to 826.0 Hz | | | 0.167 2 | Hz % |
| $V_{IN, RES}$ | Input voltage resolution | | 0.05 | | V |
| $V_{IN, CONFIG}$ | Input voltage range | 0.0 | | 16.0 | V |

MECHANICAL

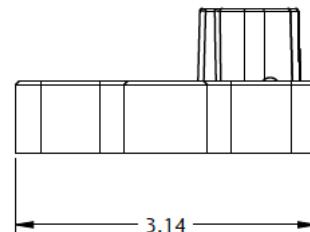
FRONT VIEW



TOP VIEW



SIDE VIEW



Measurement Units: Inches

Recommended Mating Connectors:

Deutsch DT06-045-E003
Deutsch DT06-065-E003

Mounting:

Do not mount IO 420 with connectors facing up.